



Nulling at the Keck Interferometer

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*Exoplanet Science and Technology Fair
Von Karman Auditorium, JPL, 22 Feb 2008*



KI Overview

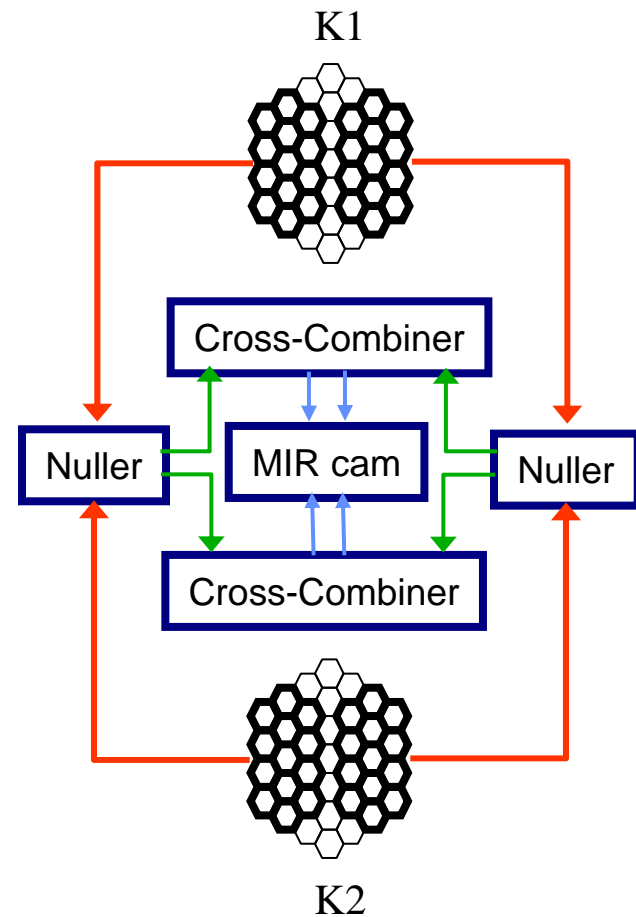
- Combines the two Keck telescopes as an Interferometer
 - Adaptive Optics (AO) on both telescopes
 - 2.2 μm active fringe tracking
 - Lots of other active systems
- H & K band fringe visibility mode
 - High sensitivity measurements of planet-forming regions
 - Observations of a range of astrophysical objects
- 10 μm nulling mode
 - Measure exozodiacal dust around nearby main sequence stars
 - » Improve on current SED measurements
 - » Support science planning for future exoplanet missions

Observing Modes

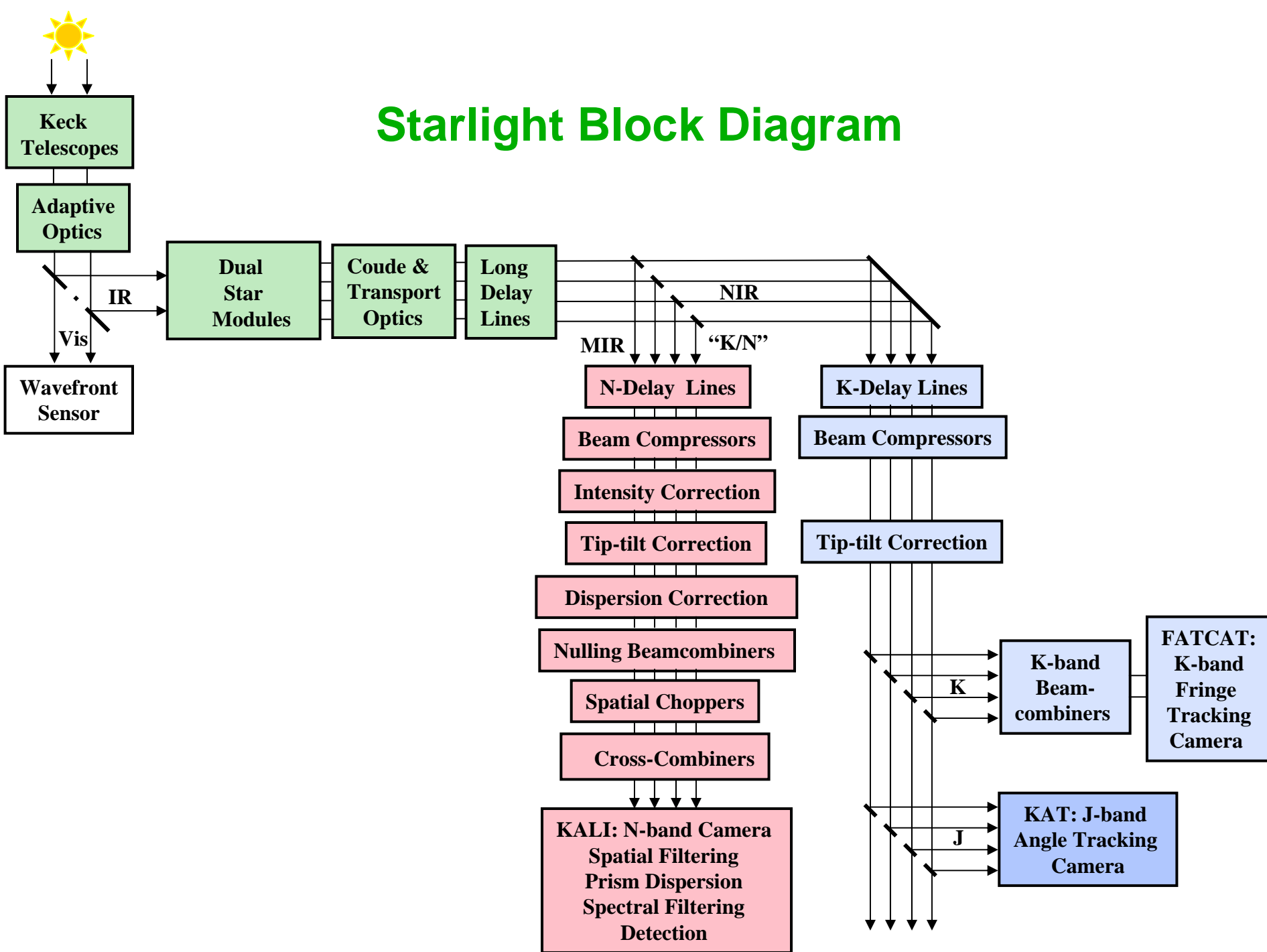
- V2 mode has been routinely available to the community since 2004
- Nuller has recently completed its development & validation, including shared-risk-science observations
- Nuller begins its Key Science program this month. Key Science team PI's:
 - Gene Serabyn, JPL
 - Phil Hinz, Univ. of Arizona
 - Marc Kuchner, GSFC
- First shared-risk nuller science paper on observations of Nova RS Oph just accepted
 - R. K. Barry et al. "Milliarcsecond N-Band Observations of the Nova RS Ophiuchi," 2008, ApJ, accepted [arXiv:0801.4165]

Nuller Concept

- Two problems
 - Bright star
 - Bright background
- Approach: 4 beam interferometer
 - Split each Keck pupil into L and R halves
 - Null star on the two 85 m baselines (K1L+K2L; K1R+K2R) to improve the exozodi-to-star ratio (no SNR gain for ground-based obs.)
 - Combine and demodulate the nulled outputs on the short 4.1 m baseline
 - » Interferometric chopping to measure the nulled signal in a large background



Starlight Block Diagram



K1 in Interferometry basement

K2 in



Long delay
lines

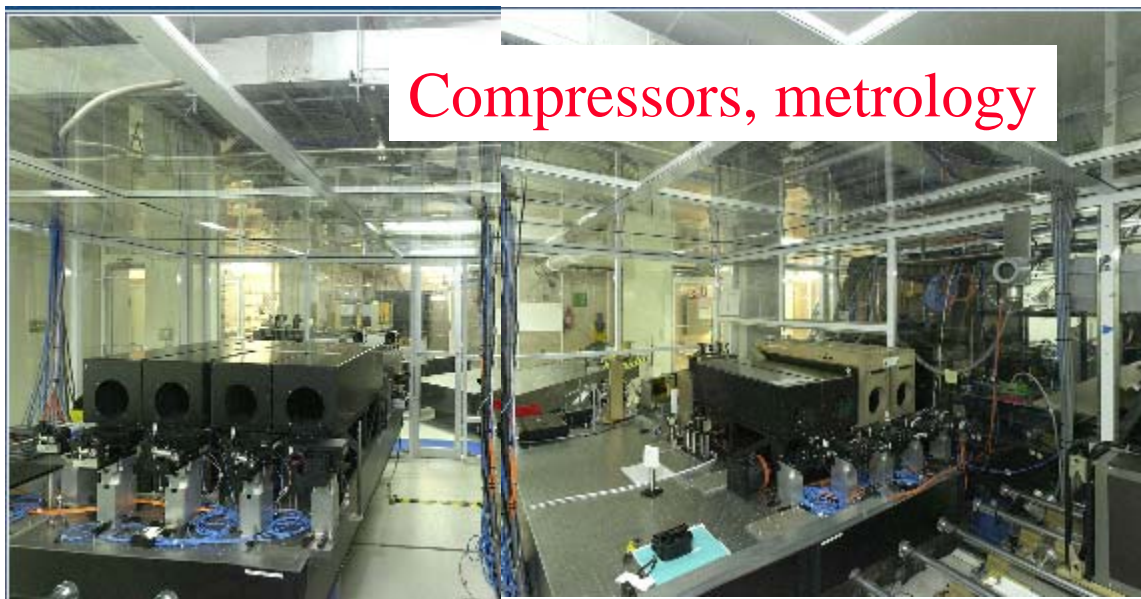
Beam
combiners

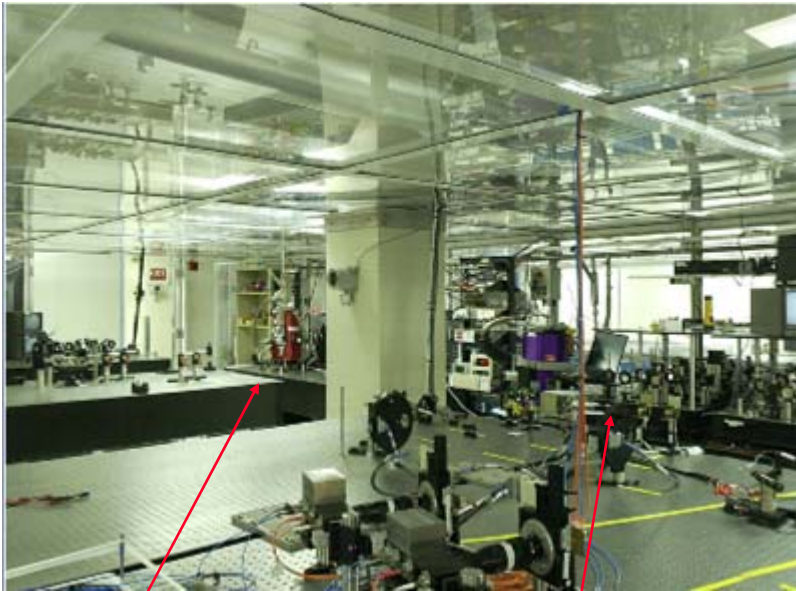
Fast delay
lines

Switchyard

See virtual tour at planetquest.jpl.nasa.gov/Keck

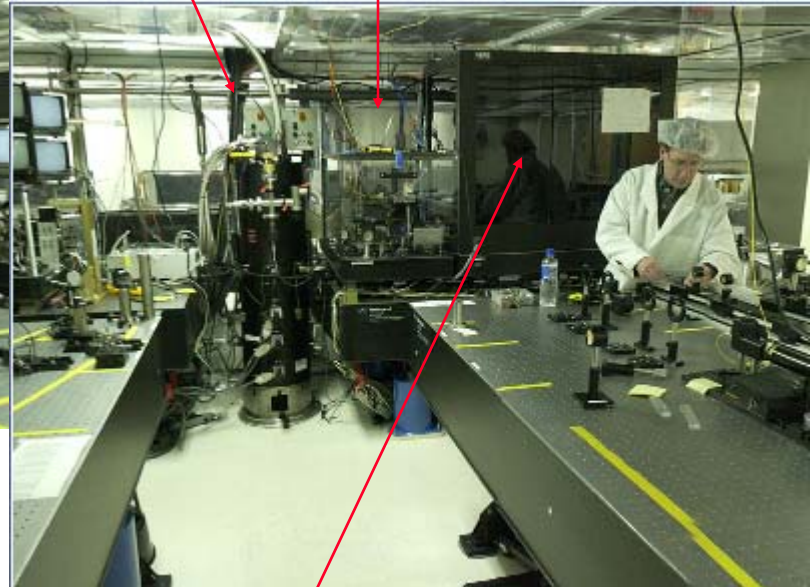
Fast delay line area





KAT

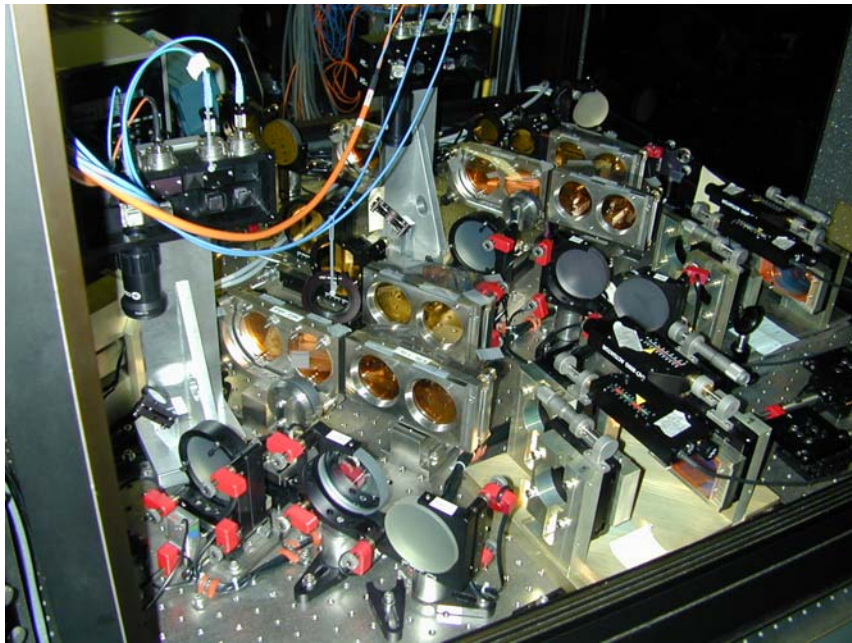
FATCAT



KALI

Nuller
Stimulus

Nuller
Breadboard

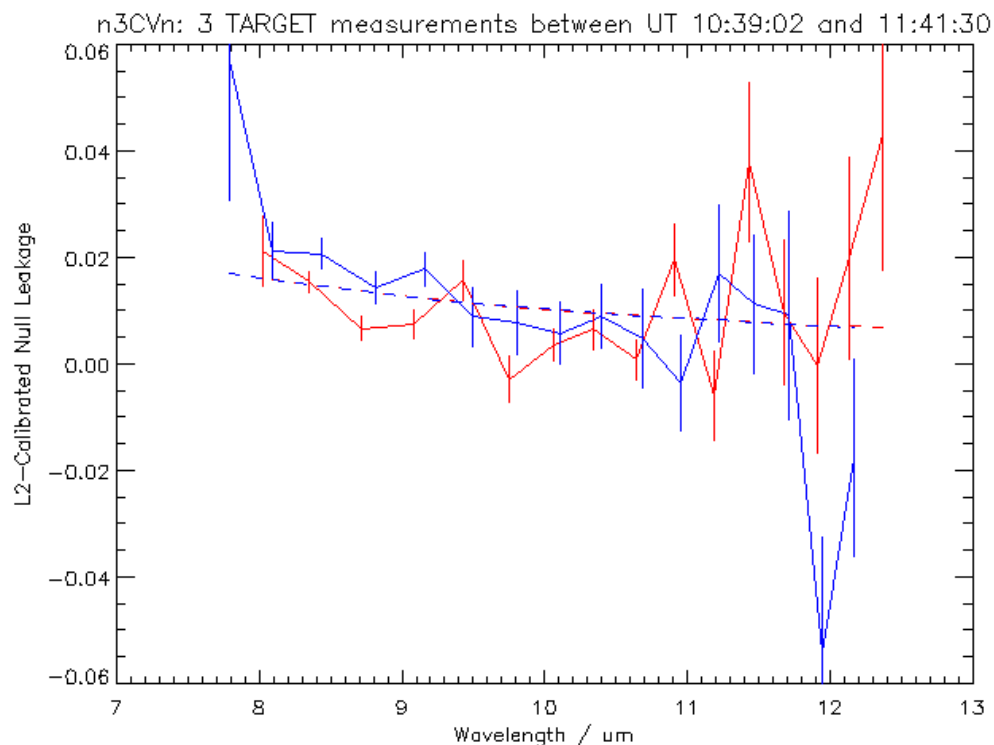


Beam combiner area

Observing scenario

Nulling

- Measure science target with interleaved calibrators
- From calibrators, compute “system leakage”, i.e., $1 / \text{Null Depth}$
- Calibrated Leakage is $L_{\text{science}} - L_{\text{system}}$
 - Accuracy of this quantity is key performance metric
- Analogous to V2 ops scenario



Everything degrades the null

error budget terms for 1% leakage

1	Differential OPD (windowed)	$L = \frac{1}{4} \sigma_{\phi 1 - \phi 2}^2$	300	(nm rms)
2	Intensity balance	$L = \frac{1}{4} [1 - 4I_1 I_2 / (I_1 + I_2)^2]$	50.0%	Δ , relative I difference btwn arms (%)
3	Intensity fluctuations	$L = 1/8 \sigma_{Ii}^2$	28.0%	σ_{Ii} , total I rms each arm (%)
4	Pure image rotation	$L = \frac{1}{4} \theta^2$	12	θ , rotation (deg)
7a	Static tilt with diff-limited det. Pinhole	$L \cong 0.4 (tp)^2$	0.160	t, total vector tilt <i>difference</i> (waves)
7b	Dynamic tilt w/ diff-limited det. pinhole	$L \cong 0.4 (tp)^2$	0.160	t, total vector tilt difference (waves)
7e	Ordinary shear with diff-limited det. pinhole	$L \sim 0.4 s'^2$	0.160	s', relative shear (frac of beam diameter)
8	Focus + astigX,Y w/ diff-limited det. pinhole	$L \cong 3 w^2$	0.058	w, total rms phase difference in those modes (waves)
9	Coma (4 terms) w/ diff-limited det. pinhole	$L \cong 0.8 w^2$	0.110	w, total rms phase difference in those modes (waves)
14b	Amplitude curvature across pupil	$L = (1/48) (\Delta)^2$	0.700	Δ , peak I mismatch (%)
5	Pure s-p phase shift	$L = 1/16 \phi^2$	23	ϕ (deg)

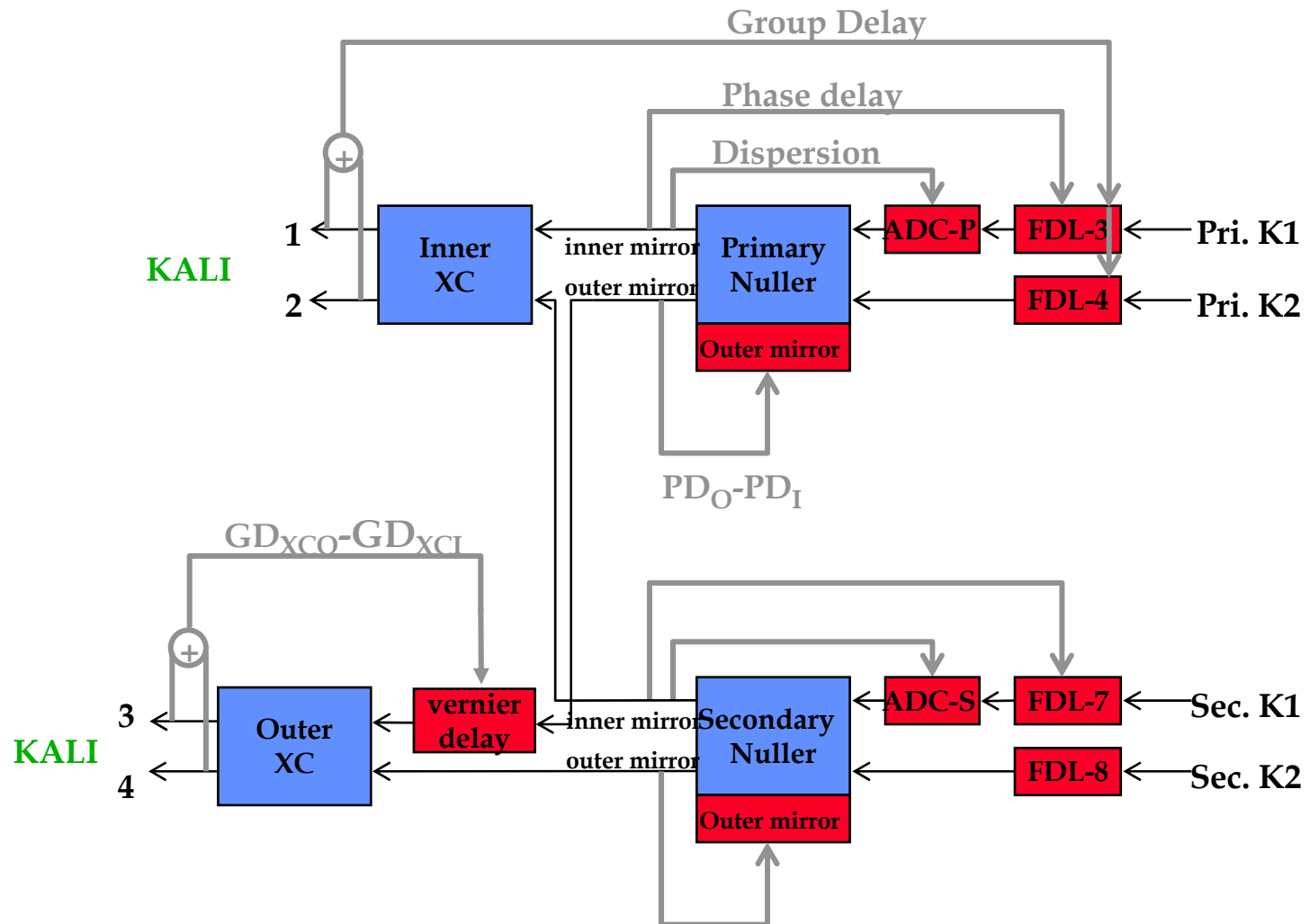
Dealing with the error budget

- Symmetry
 - Nuller beam combiner design
 - Beamtrain
 - » Coatings, rotation, etc.
- Spatial filtering
 - Camera has a $1.4 \lambda / D$ pinhole (+ other selections)
- Pointing and shear
 - Flux peak on bright star before each cluster
 - Automatic shear adjust for each star
- Cophasing
 - 300 nm rms needed for 1% leakage
 - Atmospheric moves 300 nm in 10 ms
 - 10 μ m sources don't have enough SNR in 10 ms for compensation
 - » Use 2 μ m system for fast tracking
 - Uses feedback control for the Fringe Tracker
 - Uses feedforward control to the Nuller
 - » Use 10 μ m system for slow tracking

Laser metrology and accelerometers

- External metrology
 - Measures common mode pathlengths from basement to telescope – 4 systems
- Internal metrology
 - Measures non-common mode pathlengths from fringe tracker and nuller to wavelength split – 4 differential systems
- Delay line metrology
 - Local delay line servo control – 8 systems
- Telescope accelerometers – 15 per telescope
- Implemented transparently to the fringe tracker and nuller

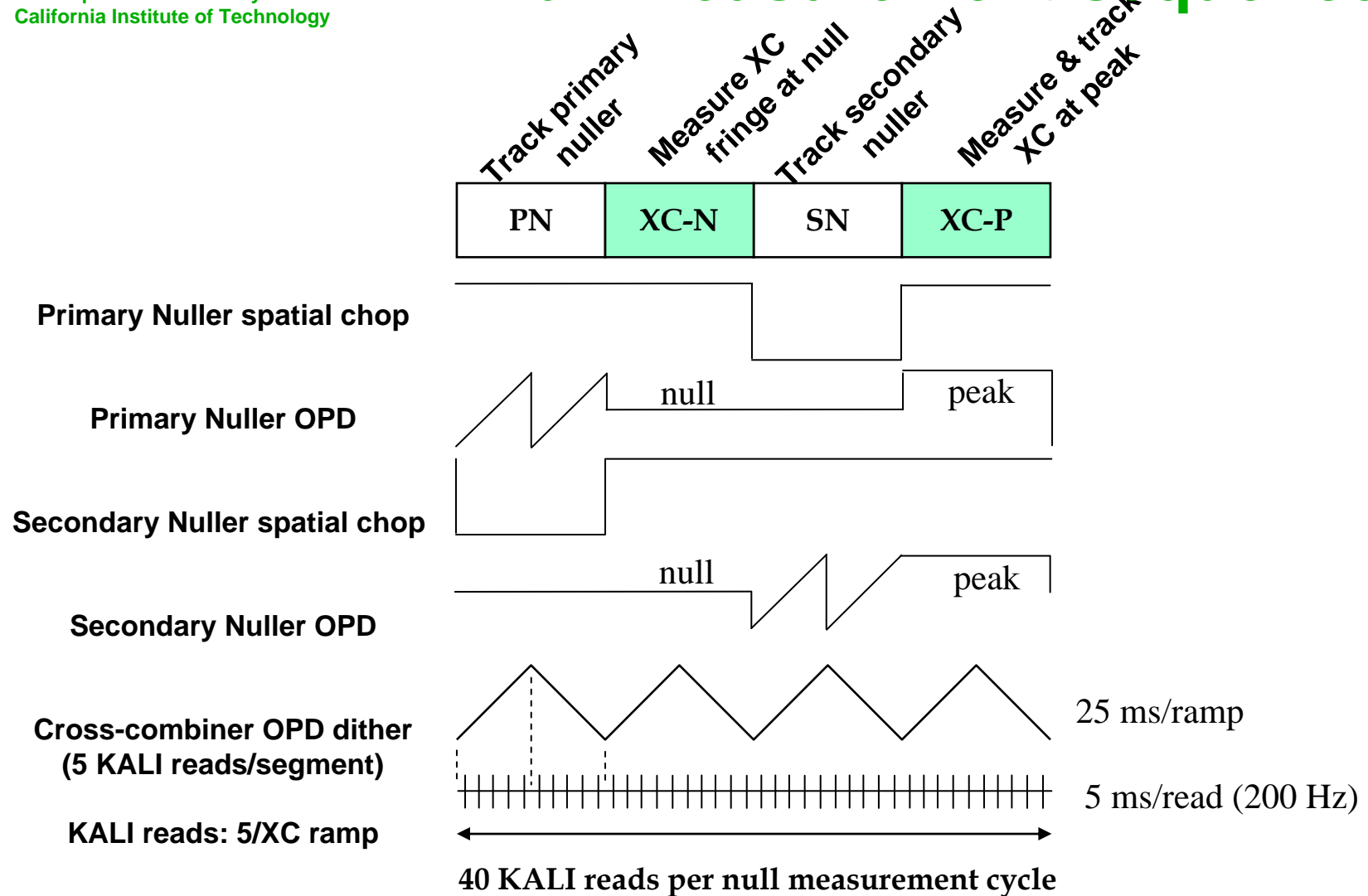
10 um starlight control loops



Multiplexing

- Laser metrology + 2 μm fringe tracking + 10 μm fringe tracking all simultaneous via WDM
 - Nuller is more problematic
 - » 1 wavelength, 1 camera: 3 fringe trackers
- A second issue – total flux calibration
 - V^2
 - » Measure fringe power N^2V^2
 - » Measure total flux N
 - » Compute normalized V^2
 - Nulling
 - » Measure coherent “null” power N_L with both MMZs at Null
 - How to get N ?
 - » Best approach for us is to measure coherent “peak” power with both MMZs at peak
- Leads to time-multiplexed sequence

Null measurement sequence



This is the acquisition-mode sequence. The science-mode sequence spends more time at null, disables the spatial choppers, and servos the long baselines to directly minimize the null leakage